gratin Documentation

Release latest

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CONTENTS

1	Getti	ng started
		Training
		Tests on simulations
	1.3	Experimental trajectories
2	Insta	llation
3	Cont	
	3.1	Simulation-based inference
	3.2	License
	3.3	Contributors

This is the documentation of Gratin (Graphs on Trajectories for Inference).

It is a tool to characterize trajectories of random walks, i.e. motion driven by random fluctuations. This type of motion is observed at various scales and in a wide diversity of systems. While this package was developed for the purpose of analysing experimental data coming from photo-activated localization microscopy (PALM) experiments, nothing prevents it from being used on random walk recordings coming from other experimental setups and other domains !

To extract summary statistics describing trajectories, Gratin mixes two ingredients :

- an original neural network architecture using graph neural networks (GNN)
- an inference scheme : Simulation-based inference

CHAPTER

GETTING STARTED

1.1 Training

It only takes one function to train a model fitting your experimental data in terms of trajectory length, localization uncertainty, diffusivity range and time interval !

```
from gratin.standard import train_model
model, encoder = train_model(
    export_path = "/path/to/model", # indicate an empty folder where to store the model
\rightarrow once trained
   num_workers = 4, # number of workers used to simulate trajectories during the_
→training phase
    time_delta = 0.03, # time separating two successive position recordings in your
→trajectories (exposure time of the camera)
   log_diffusion_range = (
        -2.0.
        1.1,
   ), # log-diffusion is drawn following a truncated centered gaussian in this range
   length_range = (7, 35), # length is drawn in a log-uniform way in this interval
   noise_range = (
        0.015.
        0.05.
   ), # localization uncertainty, in micrometers (one value per trajectory)
   max_n_epochs = 100 # Maximum epochs on which to run the training.
   )
```

1.2 Tests on simulations

Once the model is trained, you can check its performance on simulated data using the plot_demo() function. This will print the mean absolute error of the prediction of the anomalous diffusion exponent, and the F1 score of the random walk model classification task. This also plots embeddings of trajectories.

Note that you can specify traits of the trajectories on which you wish to test it, using the same parameters as the train_model() function. This is useful if you wish to test the model on data different from what it has been trained on. See *Simulation-based inference* for more details about the training procedure and the considered types of random walk.

from gratin.standard import load_model, plot_demo
model, encoder = load_model(export_path="/path/to/model")
plot_demo(
 model,
 encoder,
 length_range = (7, 55), # these values can differ from those used during training
 noise_range = (0.015, 0.05)
)

1.3 Experimental trajectories

Finally, to use a trained model to get embeddings of your own trajectories along with predictions of the anomalous diffusion exponent and of the random walk type, you can use the following function, where trajectories is a list of (. ,D) Numpy arrays representing D-dimensional trajectories (coordinates are assumed to be chronologically ordered).

```
from gratin.standard import get_predictions
df = get_predictions(model, encoder, trajectories)
# Returns a pandas DataFrame with prediction results
```

All this is illustrated in the example notebook here.

CHAPTER

TWO

INSTALLATION

To install Gratin on your machine, run

pip install gratin

Note: Gratin relies on the torch-geometric package, the installation of which depends on your version of CUDA and Torch, as well as your OS. Note that it is **not mandatory to have a graphic card at all** to run Gratin.

You'll find here the one-line-command that will install it on your machine.

CHAPTER

THREE

CONTENTS

3.1 Simulation-based inference

Simulation-based inference is when blah blah...

3.2 License

The MIT License (MIT)

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3.3 Contributors

This work was developed by Hippolyte Verdier (e-mail) during his PhD at the Decision and Bayesian Computation lab at the Institut Pasteur, funded by Sanofi.

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- genindex
- modindex
- search